

# Control Data Systems

## Industrial Wireless Communications



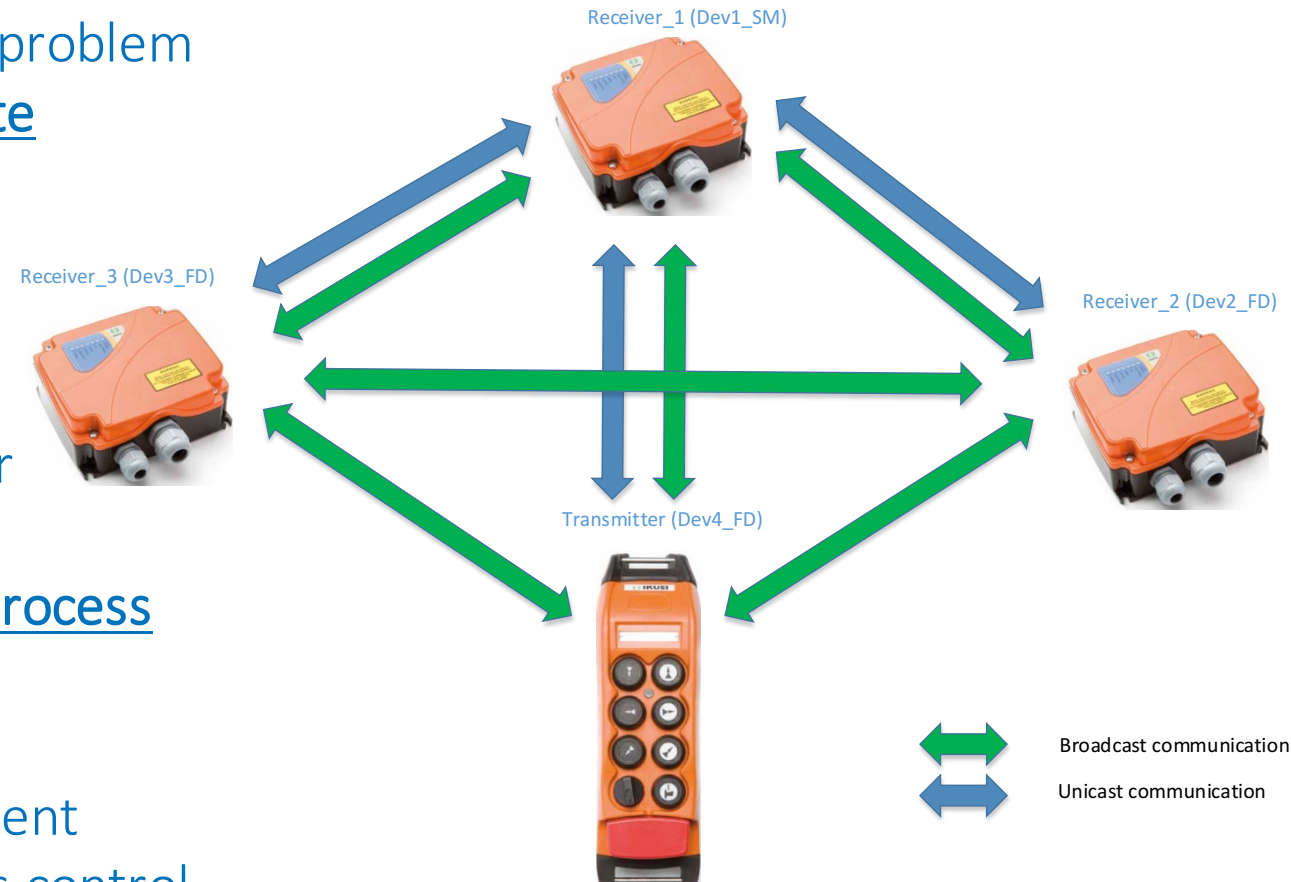
## Use case 1 – Industrial Remote Controls

- End User is IKUSI VELATIA SPAIN, Remote Controls Division
- Remote Controls operate Industrial Cranes and Lifts
- Main requirements for the wireless network are:
  1. Reliability. Missed packets can result in potentially hazardous operation of industrial lifting equipment, followed by automatic equipment shutdown
  2. Low latency. Round trip for a control message needs to be less than 100 ms, otherwise the message is useless and discarded
  3. Security. All communication needs to be securely encrypted in order to ensure integrity and safety of the equipment's operation
  4. Fast startup. The network needs to be fully functional in less than 1s from power on



# ISA100 Remote Control – the Wireless Solution

- ISA100 Wireless was selected for solving the problem
- The network consists of 4 devices: one remote control and 3 actuators on the crane or lift equipment
- The network topology is star
- One node has the role of System Manager
- Any node can be selected as System Manager
- The System Manager node is line powered
- Each node follows the ISA100 standard join process
- The join process takes less than 1s
- There are 2 types of ISA100 messages used:
  - Unicast messages are used for management
  - Broadcast messages are used for process control





# ISA100 Remote Control - Reliability

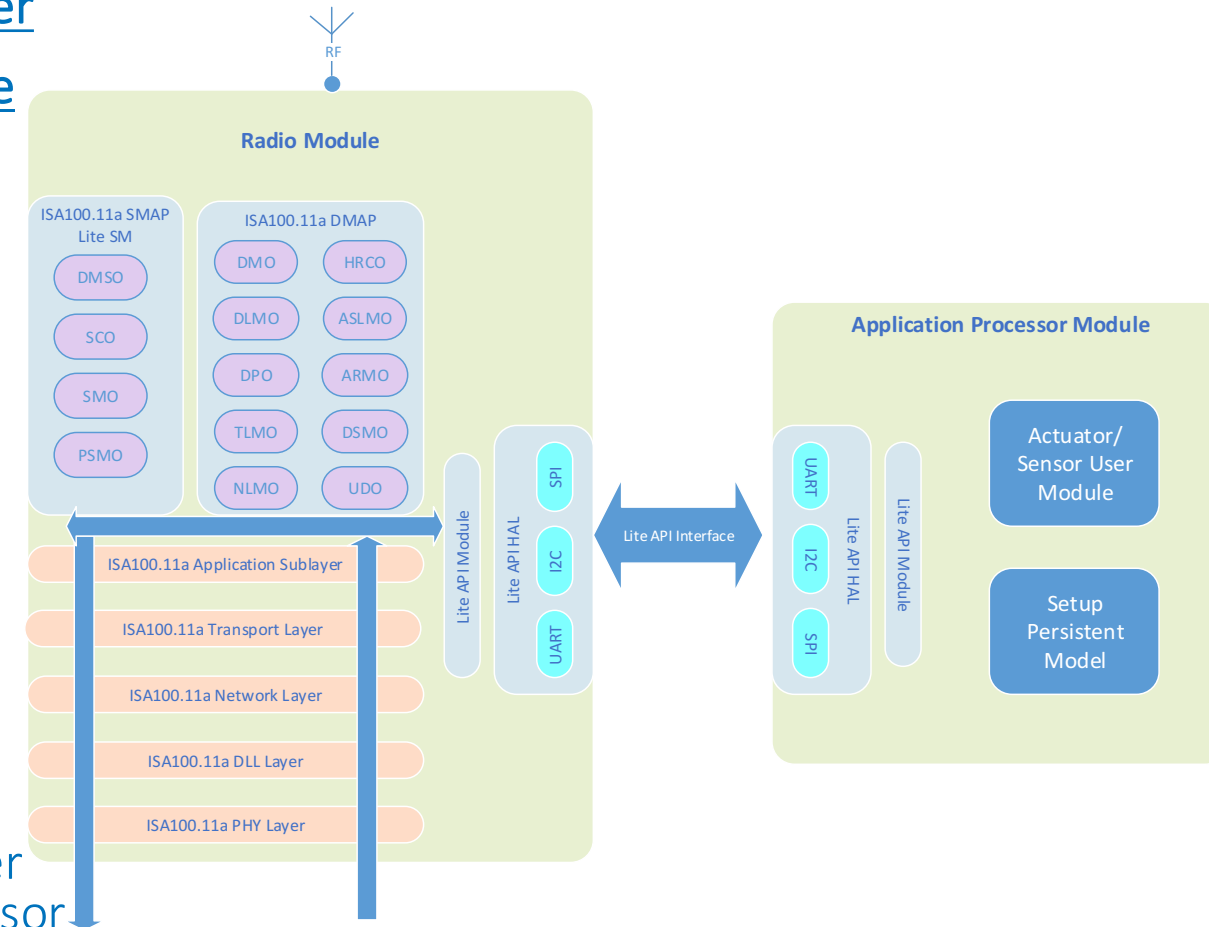
- ISA100 TDMA mechanism is used to avoid message collisions
  - Time is divided in 10 ms timeslots
  - Time slot sequence repeats after 12 slots
  - 3,000 time slots make a superframe
  - Each time slot has a dedicated role:
    - Advertisement
    - Shared transmission
    - Reception
- ISA100 Channel hopping mechanism is used to avoid interference
  - 16 channels available
  - Blacklisting mechanism

	Advertisement Tx
	Shared Tx for Join Response or unicast DPDU for each FD
	Shared Tx for Join Request
	Generic Rx
	Broadcast Shared Tx and Generic Rx(lower priority)

SuperframeOffset	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	... 2999
Device_1(SM)																
Device_2(FD)																
Device_3(FD)																
Device_4(FD)																

# ISA100 Remote Control – the Lite System Manager

- The ISA100 Network is controlled by a System Manager
- Traditionally the System Manager is running on a large computer system
- ISA100 Wireless can be optimized for a particular application
- A light version (Lite SM) of the System Manager was developed specifically for this project
- The Lite SM can run on an embedded platform
  - 32 bit ARM Cortex M3 processor
  - 91 KB Flash (code)
  - 72 KB RAM
- Any node in the network can become the Lite SM
- The Lite SM communicates via a Lite API interface over UART, SPI and I2C with an external Application Processor



# ISA100 Remote Control – the Persistent Model

- The collection of all configuration parameters of the network is organized logically into a Persistent Model
- The Persistent Model is distributed to all devices in the network
- The configuration of each device is extracted and loaded from the common Persistent Model
- The Persistent Model is distributed in binary format for efficiency
- A PC application was developed for this project to edit the Persistent Model
- The Persistent Model concept offers great configuration flexibility
- The Persistent Model can be optimized depending on the application performance requirements (size vs speed, etc.)
- All configuration parameters stored in external ROM memory

# ISA100 Remote Control – the Broadcast Mechanism

- ISA100 is flexible enough to allow for implementation extensions to the standard
- To meet the latency requirements, an extension to the ISA100 standard was developed
- The ISA100 standard defines the broadcast mechanism at DLL level (e.g. advertisements)
- The broadcast mechanism was extended to Network, Transport and Application layers
- The ISA100 standard allows for tunneling of application packets through the wireless network
- In this project the control packets are tunneled through the ISA100 network
- Control packets are generated by the transmitter application and encapsulated in broadcast messages
- The Application on the receiver de-capsulates the control packets and retains only the relevant ones
- All parameters needed for broadcast (IPv6 address, short address, etc.) are stored in the Persistent Model

# ISA100 Remote Control – the Results

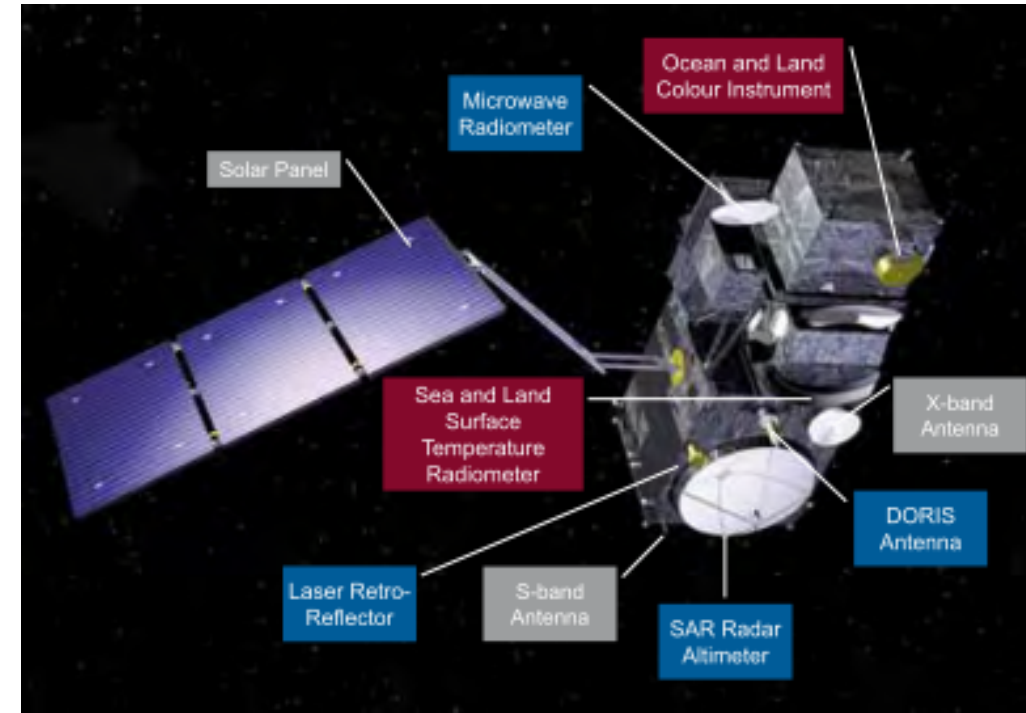
- The Lite SM capabilities (maximum size network) have been estimated at
  - 150 nodes
  - 200 links
  - 120 control packets in Queue
- Using a setup of 1 Transmitter and 3 Actuators the following performance was measured:
  - Join Duration for the entire network from power on: ~1 second
  - Minimum granted discovery duration = 380 ms
  - Control packet latency with no retry at DLL level: ~20 ms
  - Clock synchronism between any 2 nodes: < 100 us
- Future improvements
  - A Dynamic Persistent Model will support control applications for larger, mesh networks





## Use case 2 – Intra satellite communications

- End User is the European Space Agency (ESA)
- Satellite data handling systems are traditionally wired (Mil-1553b, CAN, SPI, I2C... or point-to-point connections such as RS422, SpaceWire, etc).
- Wired data systems (harnesses) pose a series of problems:
  - The increment of the dry mass of spacecraft due to harnessing is in the order of a 10%.
  - Wiring requires complex assembly (communication paths), integration and testing as spacecraft complexity increase.
  - Signal leakage requires isolation for avoiding electromagnetic compatibility issues (EMC)
  - Restriction in physical dimensions
  - High cost of late design changes
  - Possible failures of wires and connectors, risk of system malfunctioning due to EMI and risk of total failure due to any short circuit



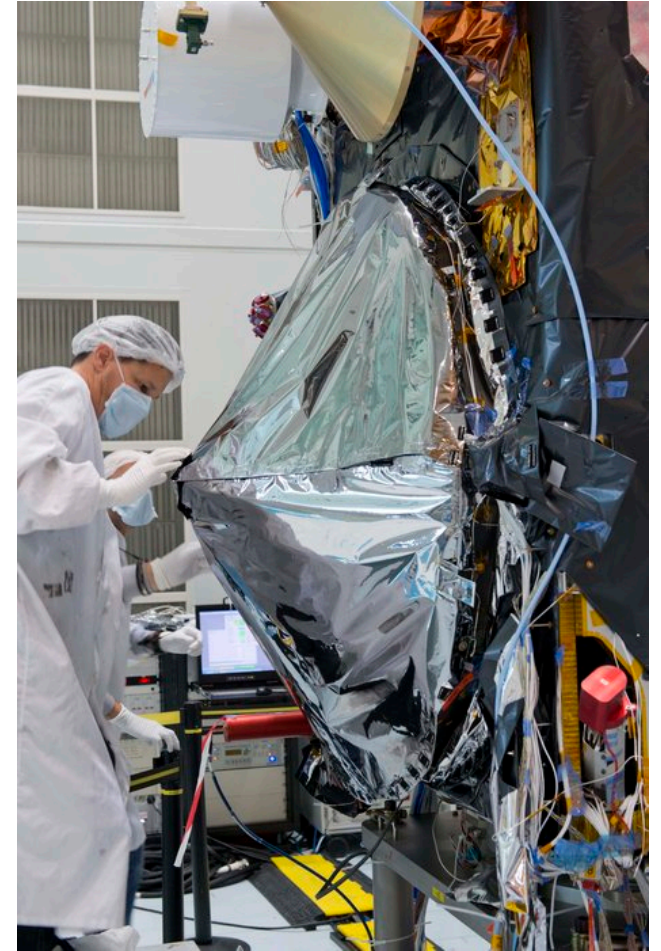
# Intra satellite communications – ISA100 advantages

- Advantages of an ISA100 Wireless harness in Satellite assembly
  - Significant reduction of mass (up to 10%) resulting in lower launch cost
  - Reduction in AIT (Assembly, Integration and Testing) effort, resulting in lower assembly costs
  - Increased reliability, resulting in a lower cost due to less redundant wires
  - Lower cost for late design changes
  - Meeting the low latency requirements for the satellite attitude control application



# Intra Satellite Communications – the Challenge

- Requirements for Intra Satellite Wireless Communications
  - Low number of nodes – sensors and actuators
  - High volume of data (10s of KB / sec) from sensors
  - Strict timings for actuators control (100s of msec)
  - Resistant to interference from other equipment
  - Must not generate interference with other equipment
  - Minimal node weight (10s of grams)
  - Low power consumption (10s of mW)



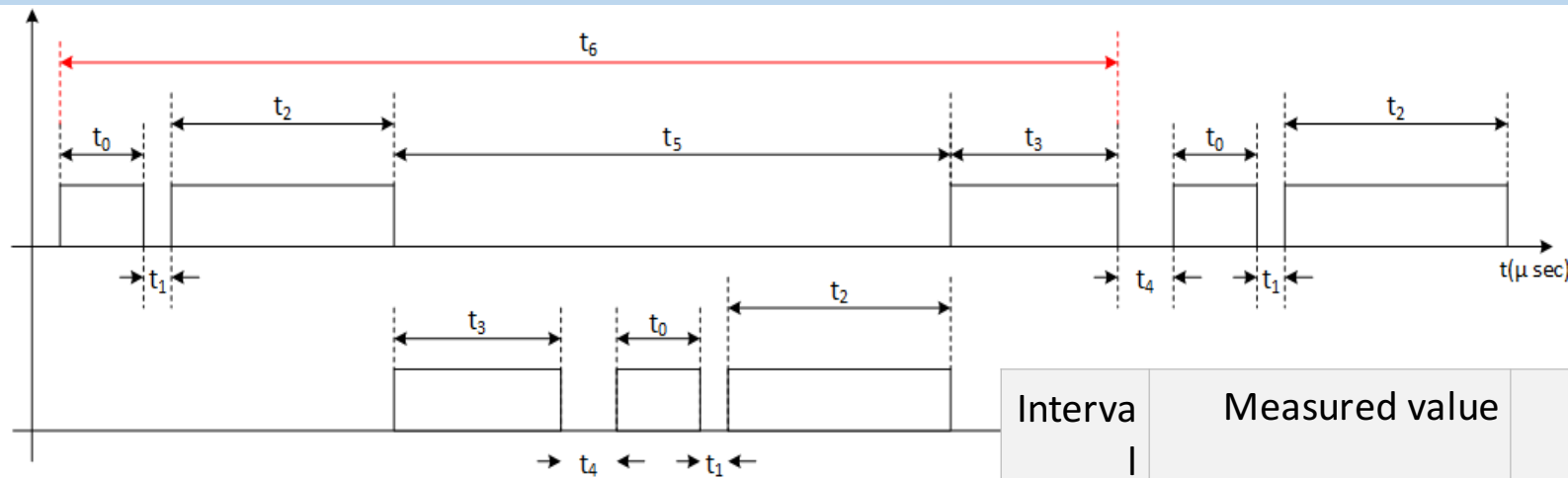
# Intra Satellite Communications – the ISA100 solution

- Due to the flexibility of the ISA100 Wireless standard, the following solution was applied to meet the requirements
  - Replacement of the physical layer
    - The 802.15.4 2.4 GHz PHY layer was replaced with 802.15.4 UWB (Ultra Wide Band)
    - The data rate was increased from 250kbps to 6.8 Mbps
    - This high data rate allows the transmission of data generated by the satellite instruments and sensors
  - Increase of the packet size
    - The packet size was increased from 128 B to 1023 B in order to optimize the network for traffic size
  - Reduction of the time slot duration
    - The time slot was reduced from 10 ms to aprox. 1,6 ms to optimize the network for low latency





# Intra Satellite Communications - Timings for 128 B frame

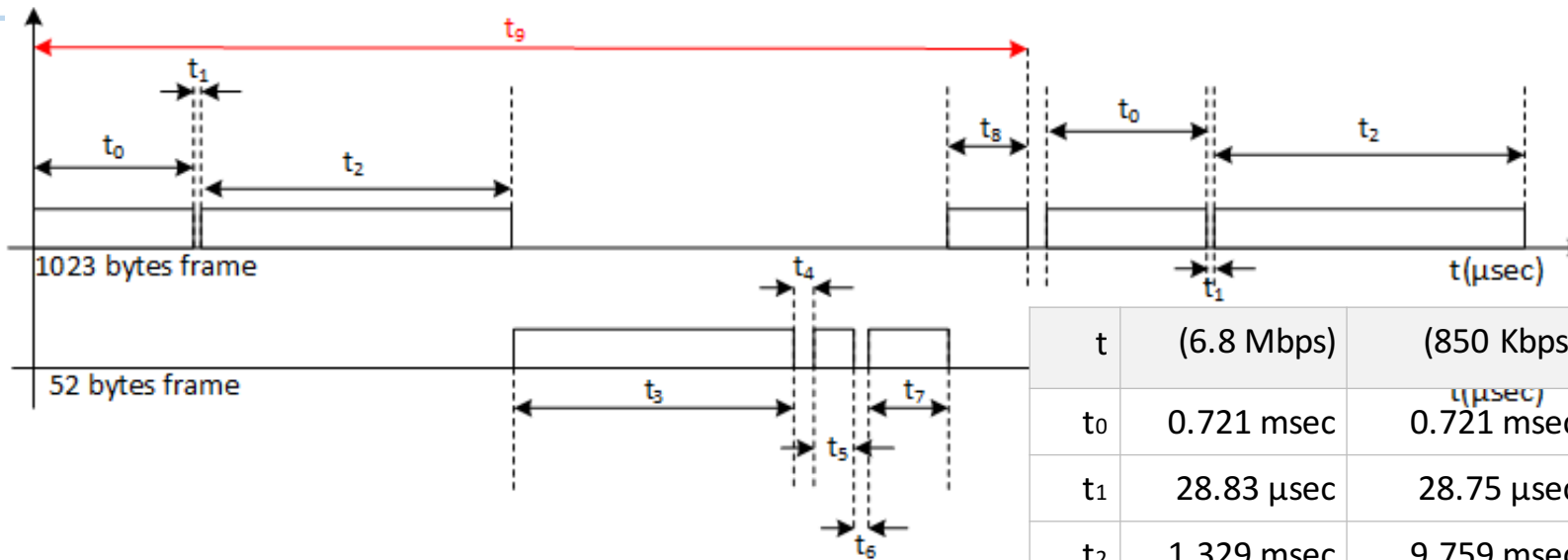


- These timings were measured for a standard ISA100 Wireless frame (128 B)
- The measurements were taken after replacing the 802.15.4 2.4 GHz PHY layer
- The new PHY layer was 802.15.4 UWB in the 5 GHz band

Interval	Measured value	Comments
t <sub>0</sub>	139.28 μsec	Write frame over SPI to DWM1000
t <sub>1</sub>	28.59 μsec	End write frame to start TX
t <sub>2</sub>	347.18 μsec	Frame transmission
t <sub>3</sub>	268.4 μsec	Read frame over SPI from DWM1000
t <sub>4</sub>	62.56 μsec	RX to TX mode switch
t <sub>5</sub>	846.01 μsec	TX to RX (t <sub>0</sub> +t <sub>1</sub> +t <sub>2</sub> +t <sub>3</sub> +t <sub>4</sub> ) wait
<b>t<sub>6</sub></b>	<b>1.63 msec</b>	<b>Slot time</b>



# Intra Satellite Communications - Timings for 1023 B frame

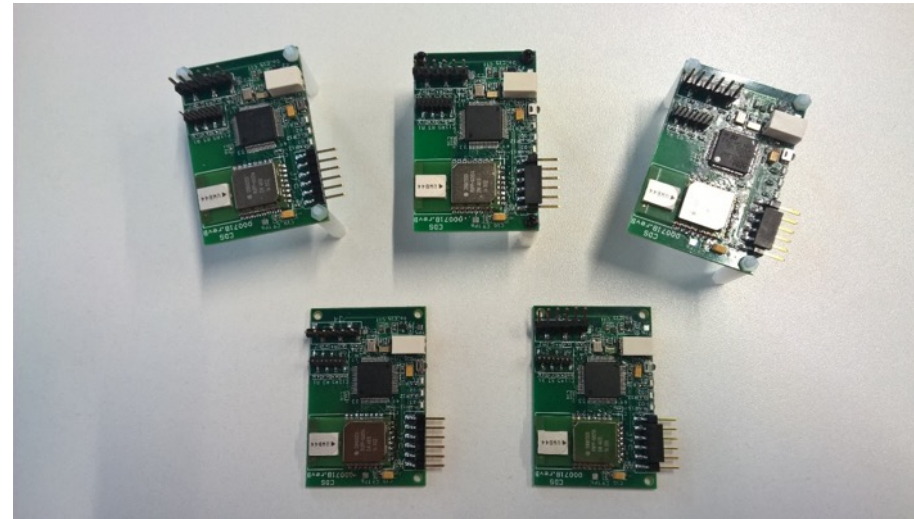


- These timings were measured for a non standard ISA100 Wireless frame (1023 B)
- The measurements were taken after replacing the 802.15.4 2.4 GHz PHY layer
- The new PHY layer was 802.15.4 UWB in the 5 GHz band
- Three different data rates were measured in the test

t	(6.8 Mbps)	(850 Kbps)	(110 Kbps)	Comments
$t_0$	0.721 msec	0.721 msec	0.716 msec	Write 1023 bytes frame over SPI
$t_1$	28.83 $\mu\text{sec}$	28.75 $\mu\text{sec}$	31 $\mu\text{sec}$	Delay before starting transmission
$t_2$	1.329 msec	9.759 msec	78.32 msec	1023 bytes frame transmission
$t_3$	1.202 msec	1.202 msec	1.2 msec	Read 1023 bytes frame over SPI
$t_4$	62.33 $\mu\text{sec}$	62.37 $\mu\text{sec}$	61.5 $\mu\text{sec}$	RX to TX mode switch
$t_5$	92.08 $\mu\text{sec}$	92 $\mu\text{sec}$	92 $\mu\text{sec}$	Write 52 bytes frame over SPI
$t_6$	29.08 $\mu\text{sec}$	29.12 $\mu\text{sec}$	30.5 $\mu\text{sec}$	Delay before starting transmission
$t_7$	0.1913 msec	0.658 msec	5.513 msec	52 bytes frame transmission
$t_8$	0.1863 msec	0.272 msec	0.187 msec	Read 52 bytes frame over SPI
<b><math>t_9</math></b>	<b>3.852 msec</b>	<b>12.74 msec</b>	<b>80.155 msec</b>	<b>Slot time</b>

# UWB Test System

- 6 nodes network
  - 1 BBR/SM
  - 2 sensors
  - 1 actuator
  - 1 provisioning device
- Test performed on 2 satellite mock-ups
  - Venus Express (at ESA)
  - Sentinel 3 (at CDS)



## Legend

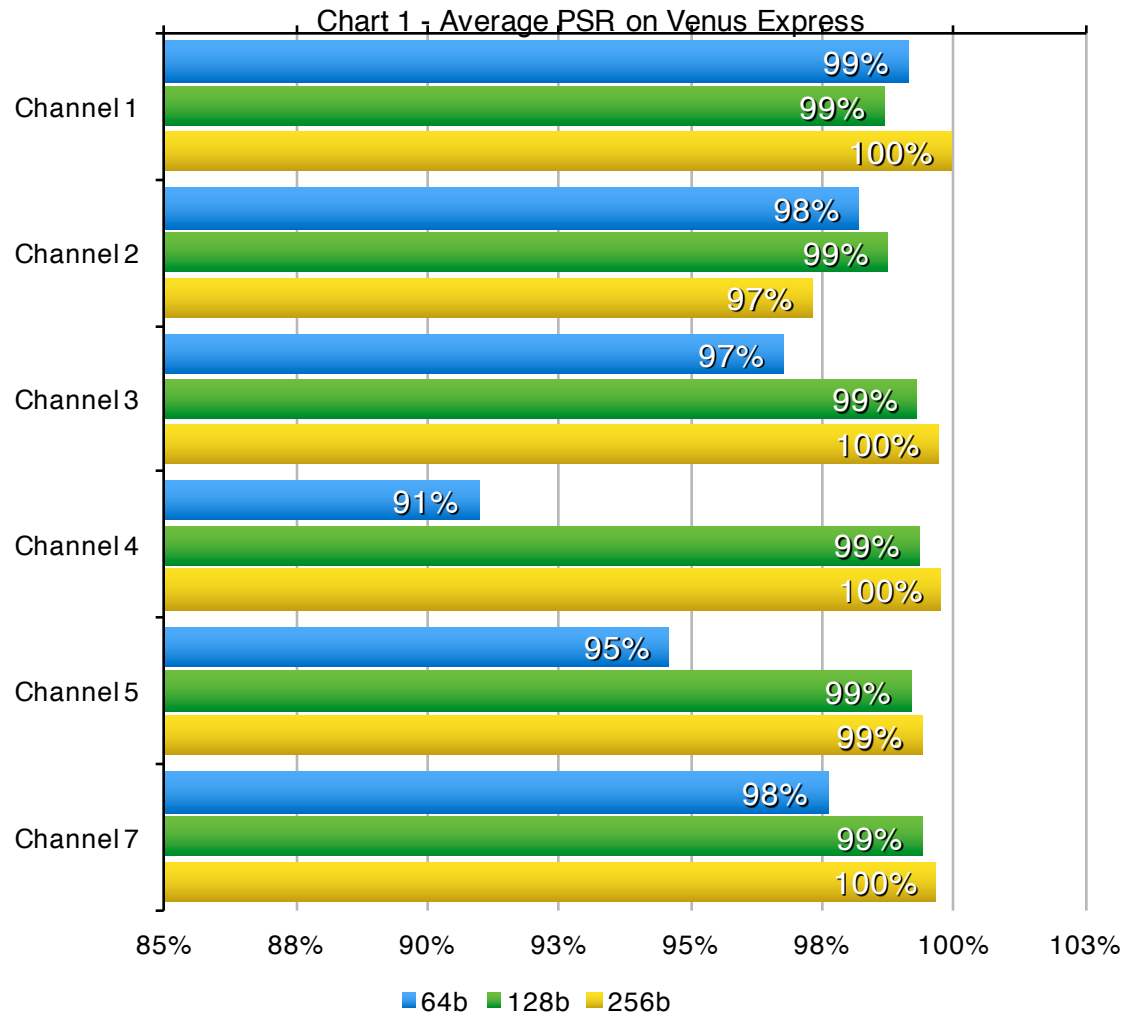
Idle slot

Receive slot

Transmit slot

	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24
01		Transmit	Receive	Receive	Receive	Receive	Receive	Receive	Receive	Receive	Receive	Receive	Receive	Receive	Receive	Receive	Receive	Receive	Receive	Receive	Receive	Receive	Receive	Receive	Receive
02		Receive	Transmit	Transmit	Transmit																				
03		Receive						Transmit	Transmit	Transmit	Transmit														
04		Receive														Transmit	Transmit								
05		Receive					Receive	Receive						Receive	Receive			Receive	Receive	Transmit	Transmit	Transmit	Transmit		

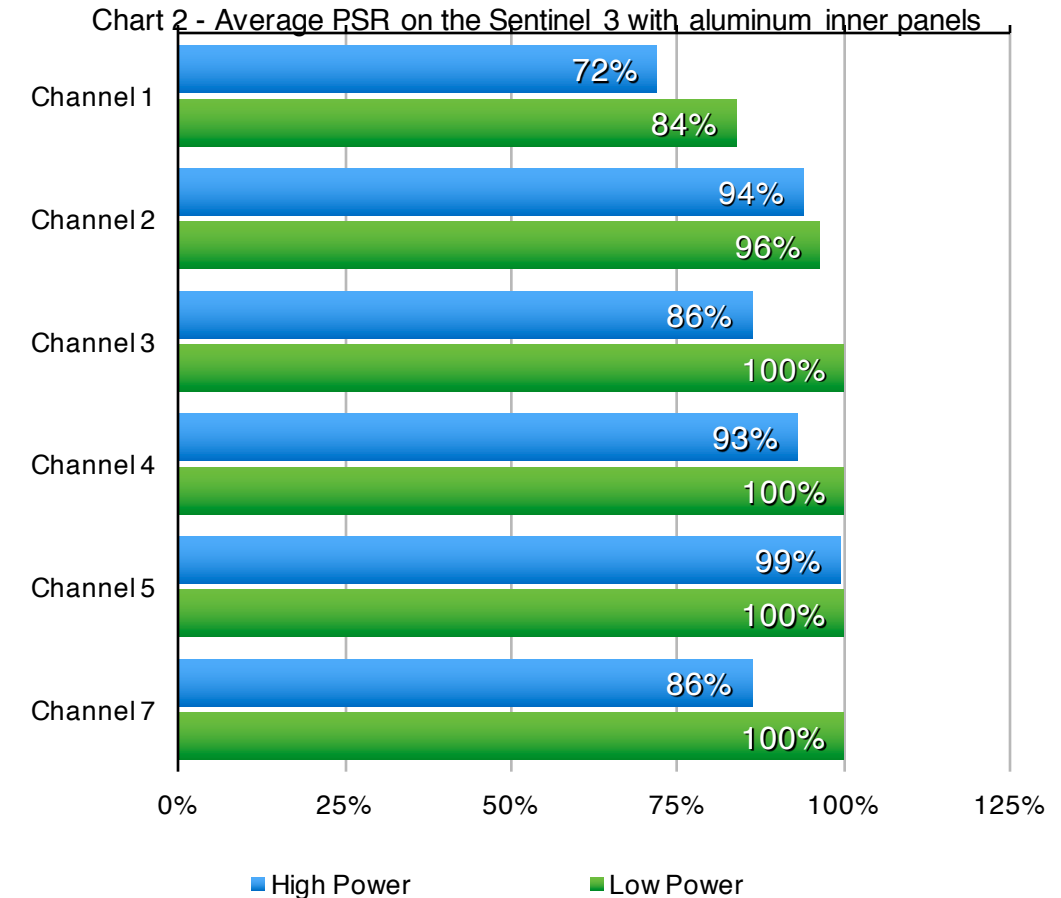
# UWB Test results – Venus Express at ESA



# UWB Test Results –Sentinel 3 at CDS



- No retries used
- 3 preambles tested: 64b, 128b and 256b
- 256b preamble performed best
- Carbon fiber vs aluminum inner panels were tested
- Carbon fiber had much better results (100%)
- High power vs low power was tested
- Low power resulted in better results



# Intra Satellite Communications – Conclusions

- ISA100 Wireless is suitable for Intra Satellite Communications
  - The ISA100 Wireless network can handle the required data throughput is 126,472 bps or 15,809 Bps (15.43 KBps) generated by the sensors and instruments
  - The ISA 100 Wireless network meets the required latency of less than 1s with actual number of less than 100 ms
  - The ISA100 Wireless network is resistant to interference and does not interfere with on board instruments and equipment
- The ISA100 Wireless network is flexible enough to allow for
  - PHY layer change to UWB with 6.8 Mbps data rate
  - Data throughput optimization by using the 1023 B frame length, in case priority is given to data acquisition from instruments
  - Latency optimization by using the 127 B frame length, in case priority is given to control of actuators



# ISA100 Wireless for Control Applications



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